

Acoustic Levitation

Levitation of single solid or liquid samples

in

ultrasonic single-axis standing-wave levitators

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- 1.1 History , fields of application
- 1.2 Features

2. Basics

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- 2.4 Optimal conditions

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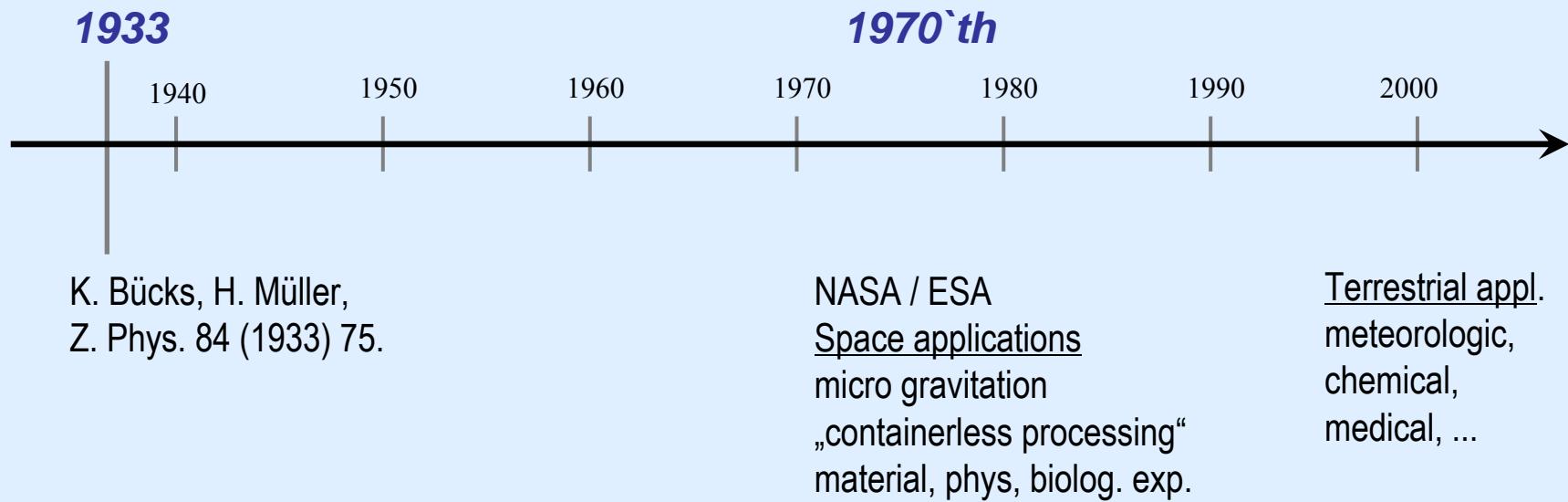
4. Engineering and design parameters

- 4.1 Soundfield

1. Overview

1.1 History

Fields of Application



1.2 Features

design :

- compact table instrument

sample

- material :
 - conductive / non conductive
 - magnetizable / non magnetizable
- aggregate state :
 - solid / liquid / gaseoushere : solid or liquid
- position :
 - stable

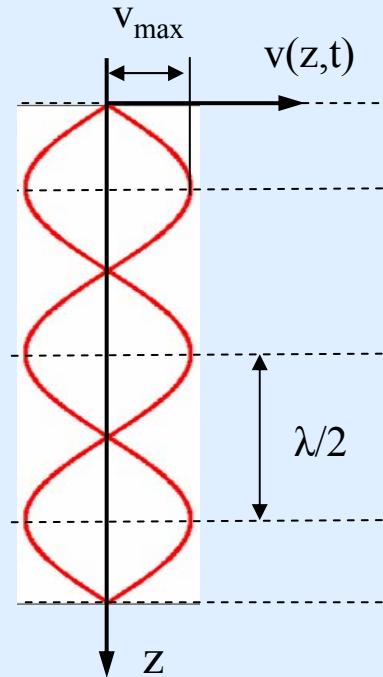
carrier fluid :

- gas / liquid
- here : gas

2. Basics

2.1 Principle : Ultrasonic standing wave

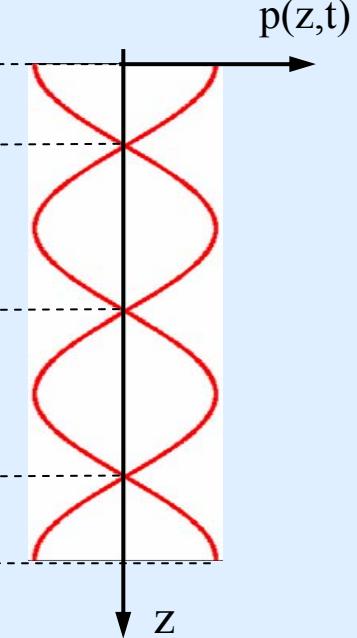
velocity profile



cyl.-sym.
axis

reflector

sound pressure profile



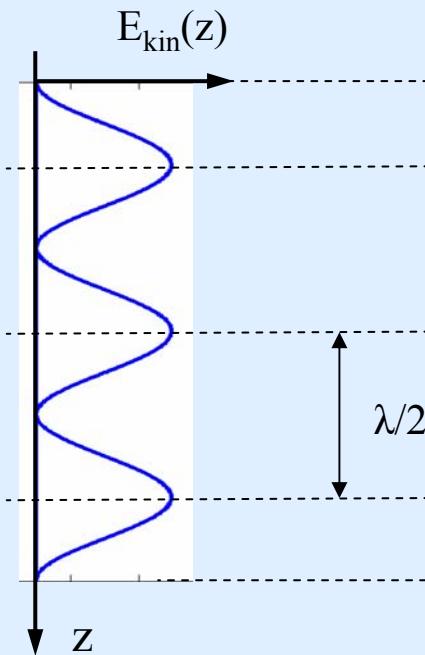
$$v(z,t) = v_{\max} \cdot \sin(k \cdot z) \cdot \sin(\omega \cdot t)$$

ultrasonic
transducer

$$p(z,t) = p_{\max} \cdot \cos(k \cdot z) \cdot \sin(\omega \cdot t)$$

2.1 Principle : Energy density in the soundfield

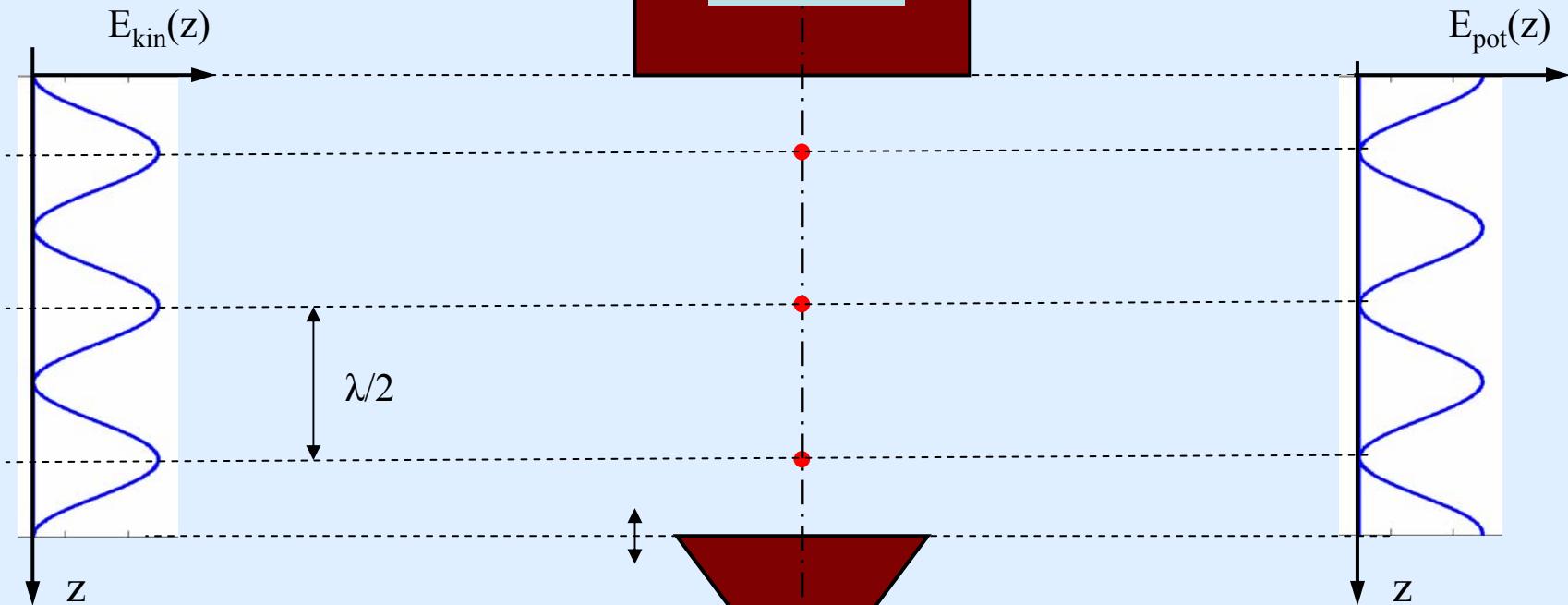
kinetic energy density



$$E_{\text{kin}}(z) = \rho_{\text{gas}}/2 \cdot v_{\max}^2 \cdot \sin^2(k \cdot z)$$

reflector

potential energy density

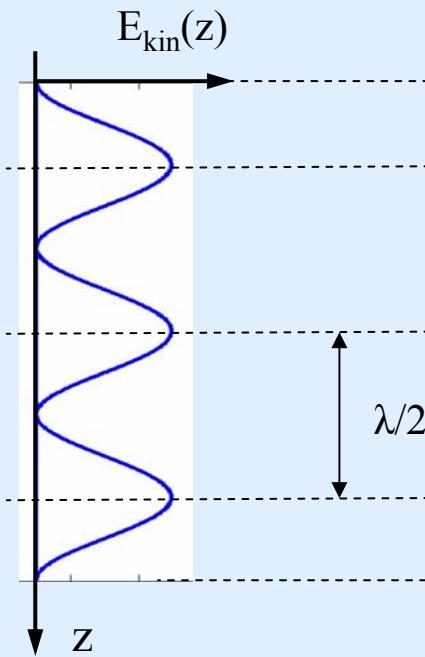


ultrasonic transducer

$$E_{\text{pot}}(z) = \frac{p_{\max}^2 \cdot \cos^2(k \cdot z)}{2 \cdot \rho_{\text{gas}} \cdot c_{\text{gas}}^2}$$

2.1 Principle : Energy density in the soundfield

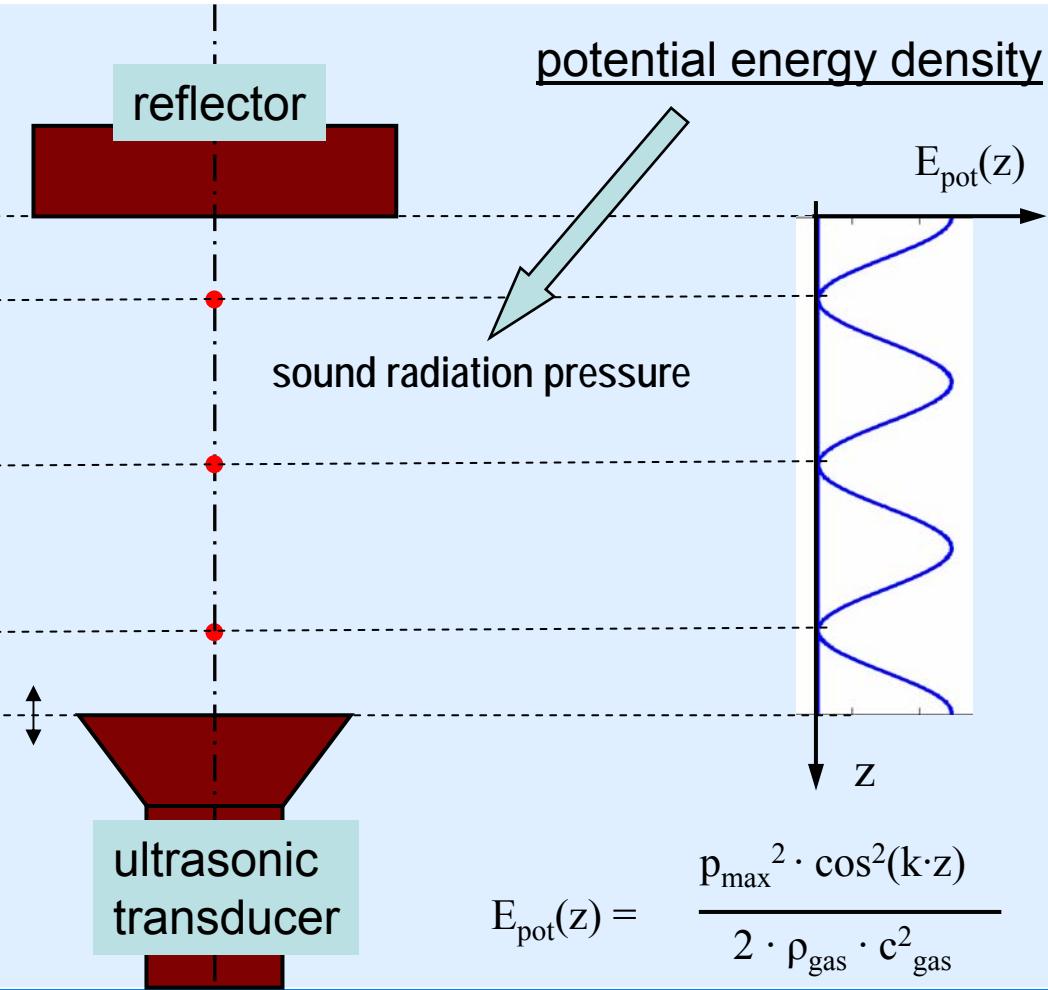
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$$E_{\text{kin}}(z) = \rho_{\text{gas}}/2 \cdot v_{\text{max}}^2 \cdot \sin^2(k \cdot z)$$

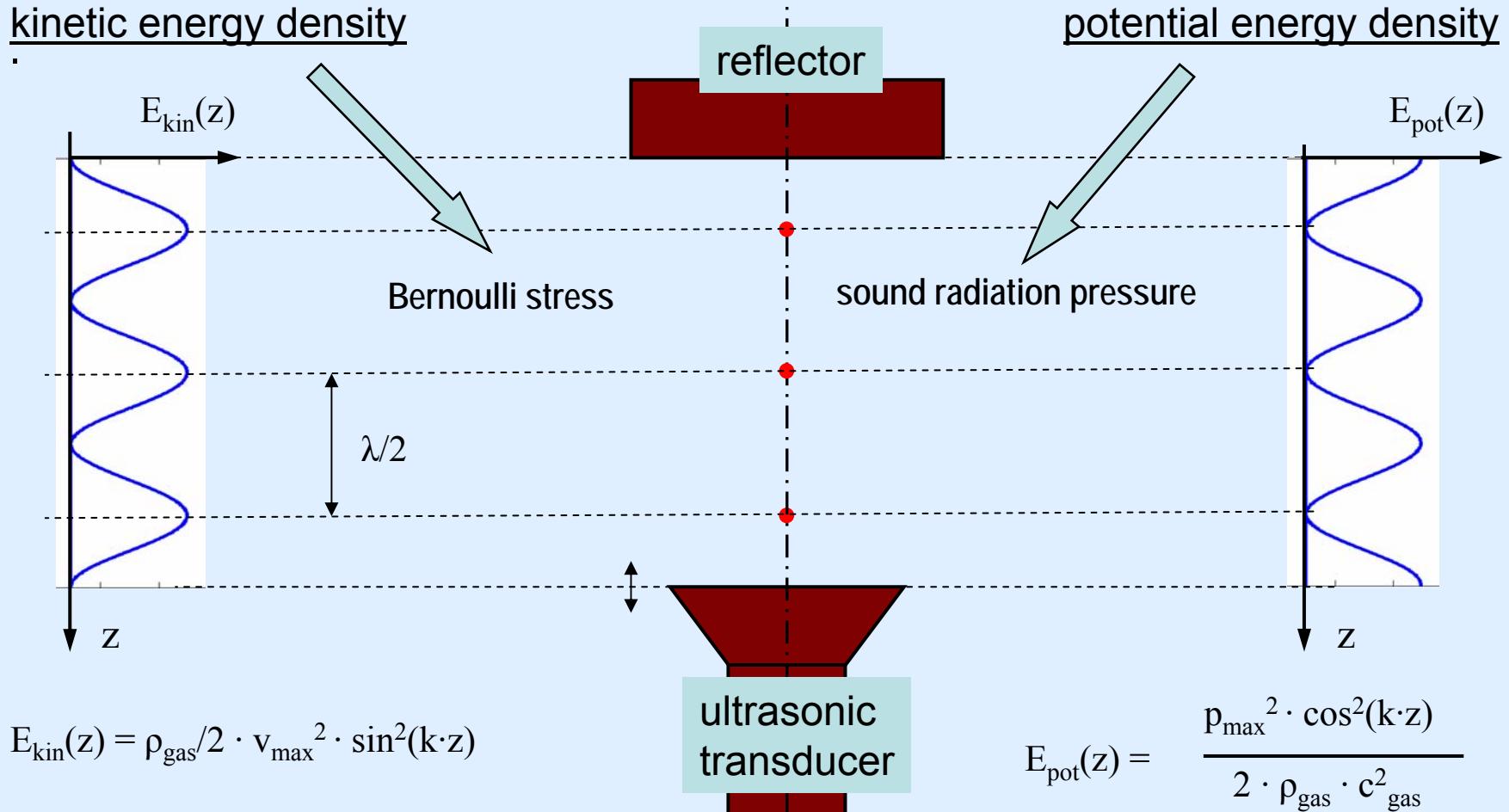
reflector

potential energy density

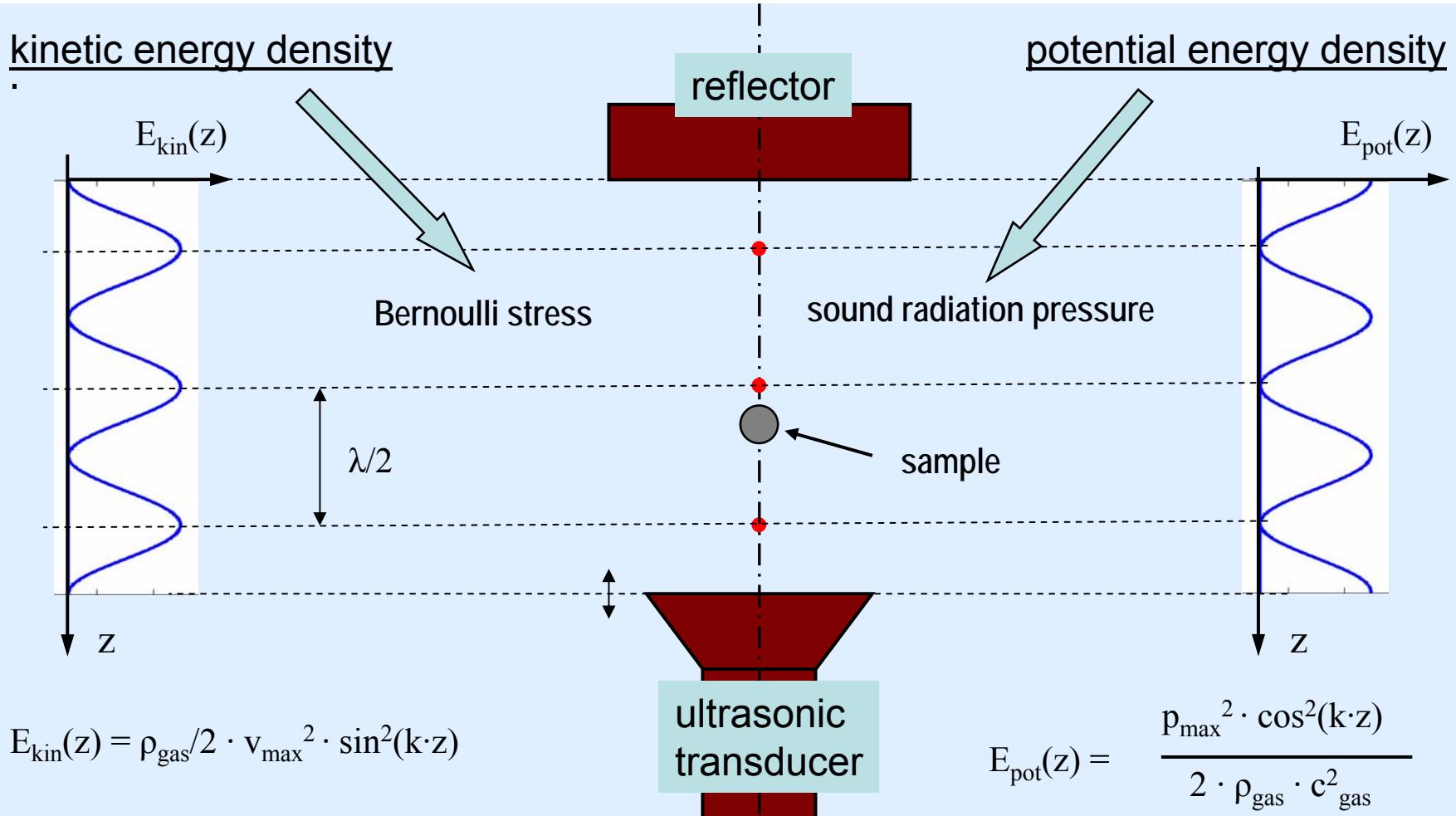


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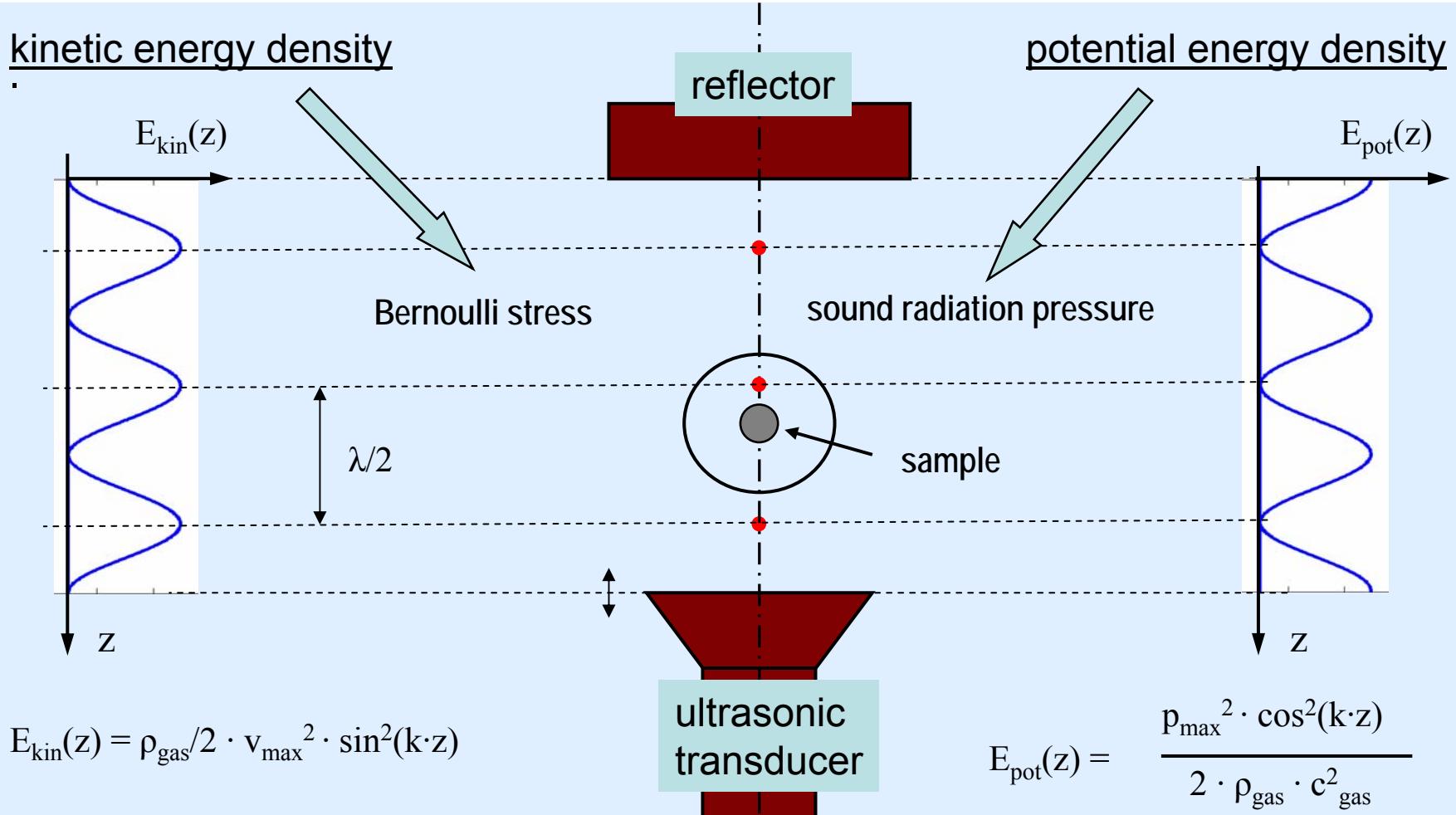
2.1 Principle : Energy density in the soundfield



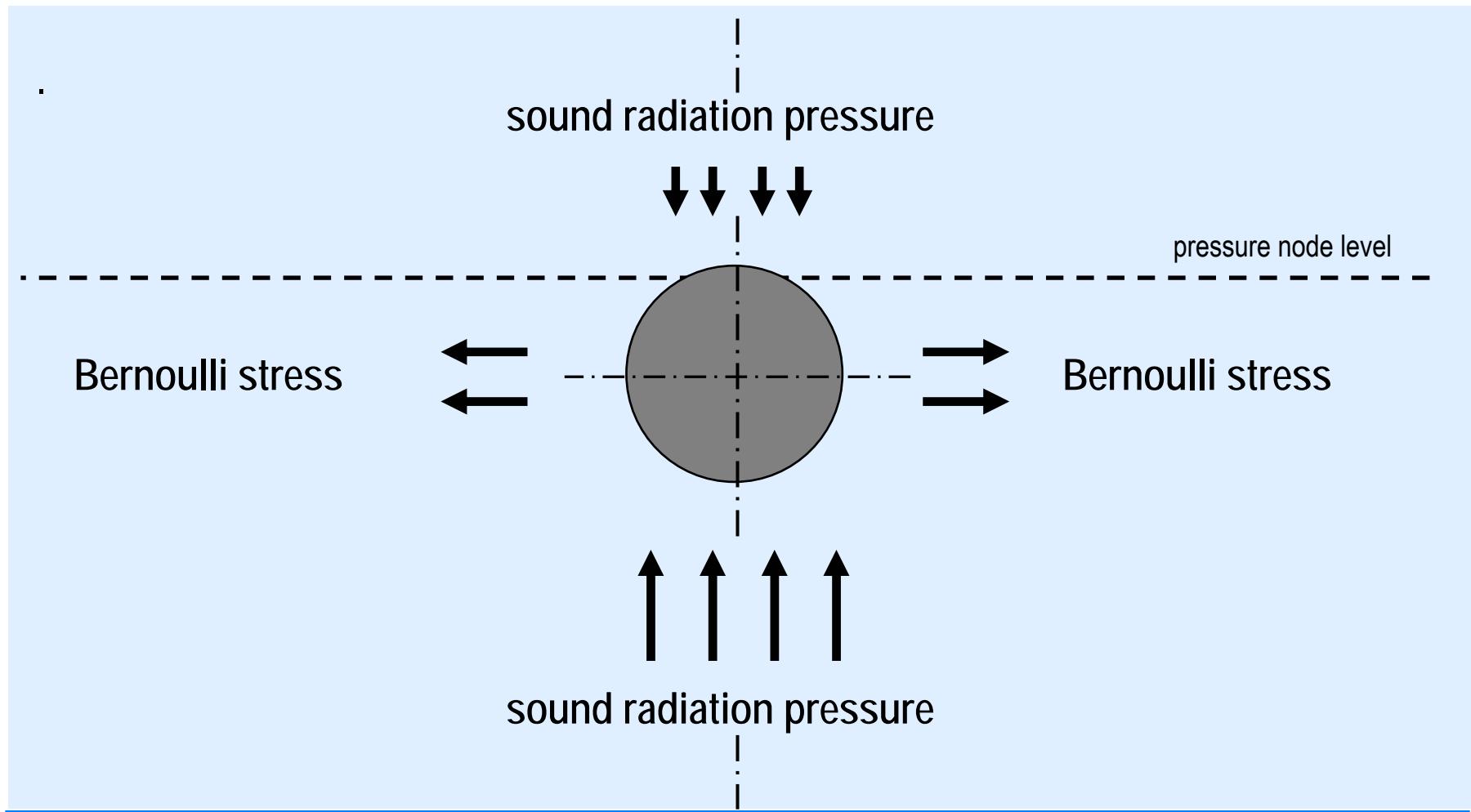
2.1 Principle : Energy density in the soundfield



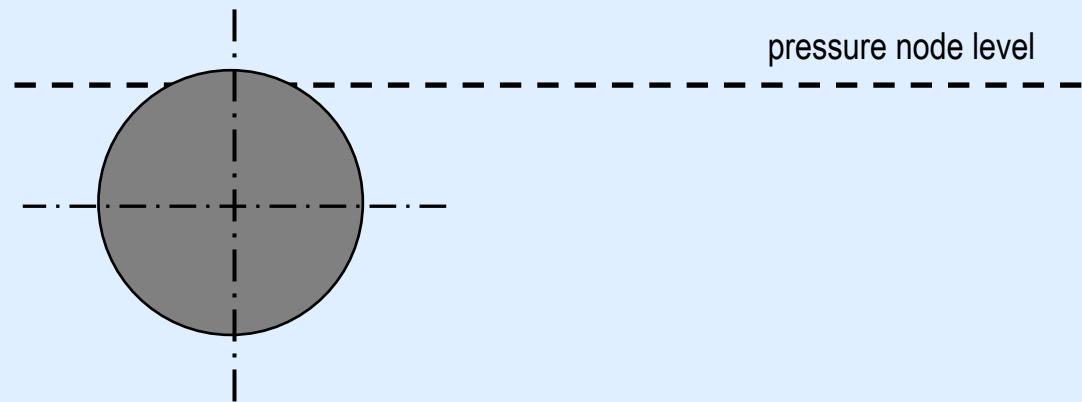
2.1 Principle : Energy density in the soundfield



2.1 Principle : Stable position near the pressure node

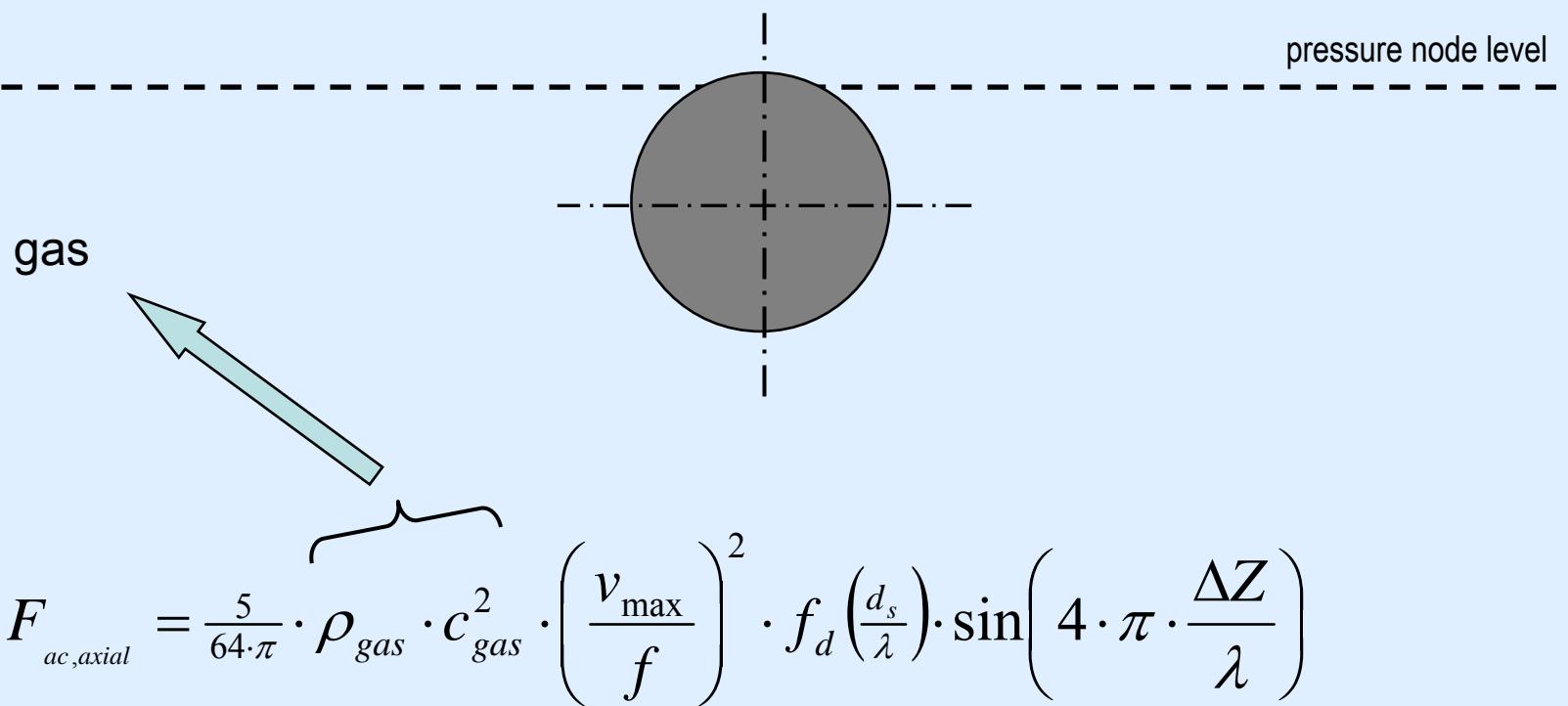


2.1 Principle : Axial acoustic levitation force



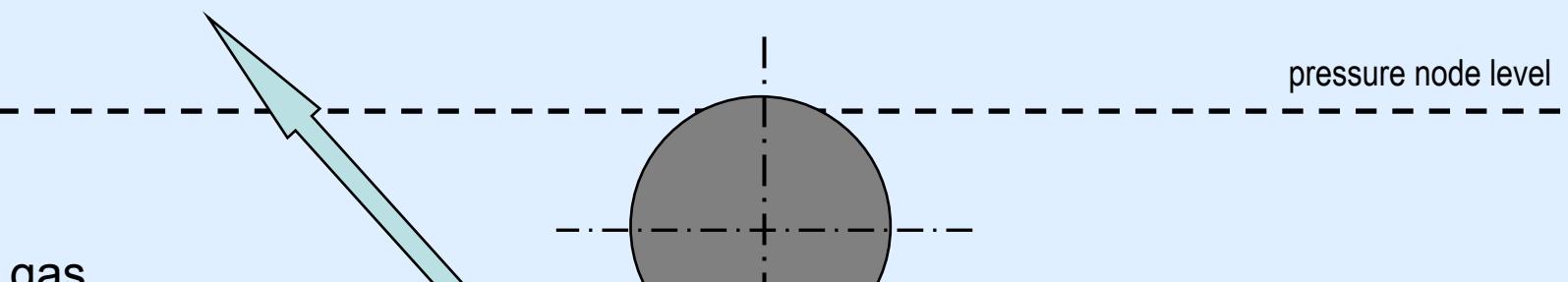
$$F_{ac,axial} = \frac{5}{64\cdot\pi} \cdot \rho_{gas} \cdot c_{gas}^2 \cdot \left(\frac{v_{max}}{f} \right)^2 \cdot f_d \left(\frac{d_s}{\lambda} \right) \cdot \sin \left(4 \cdot \pi \cdot \frac{\Delta Z}{\lambda} \right)$$

2.1 Principle : Axial acoustic levitation force



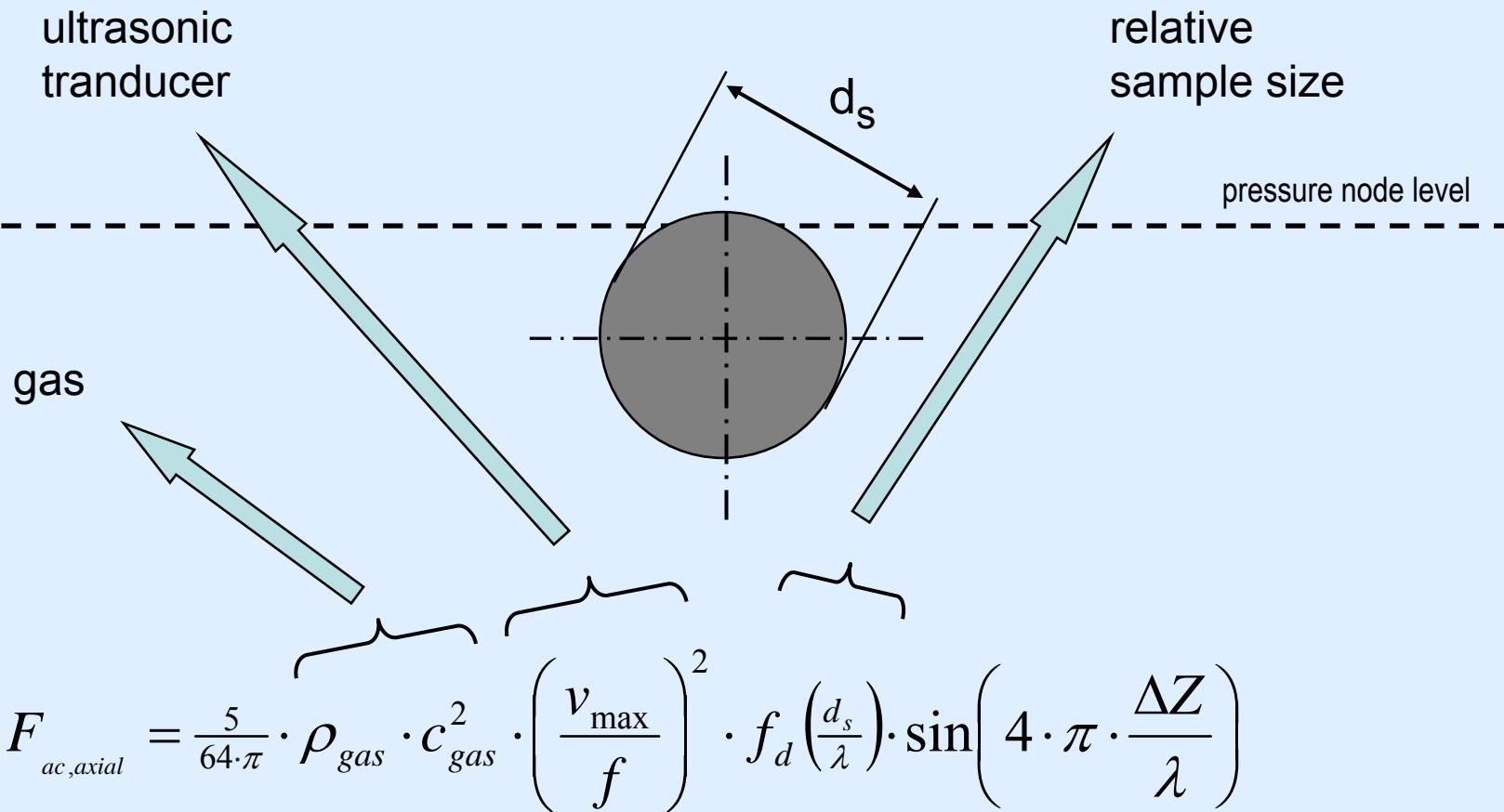
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ultrasonic
tranducer

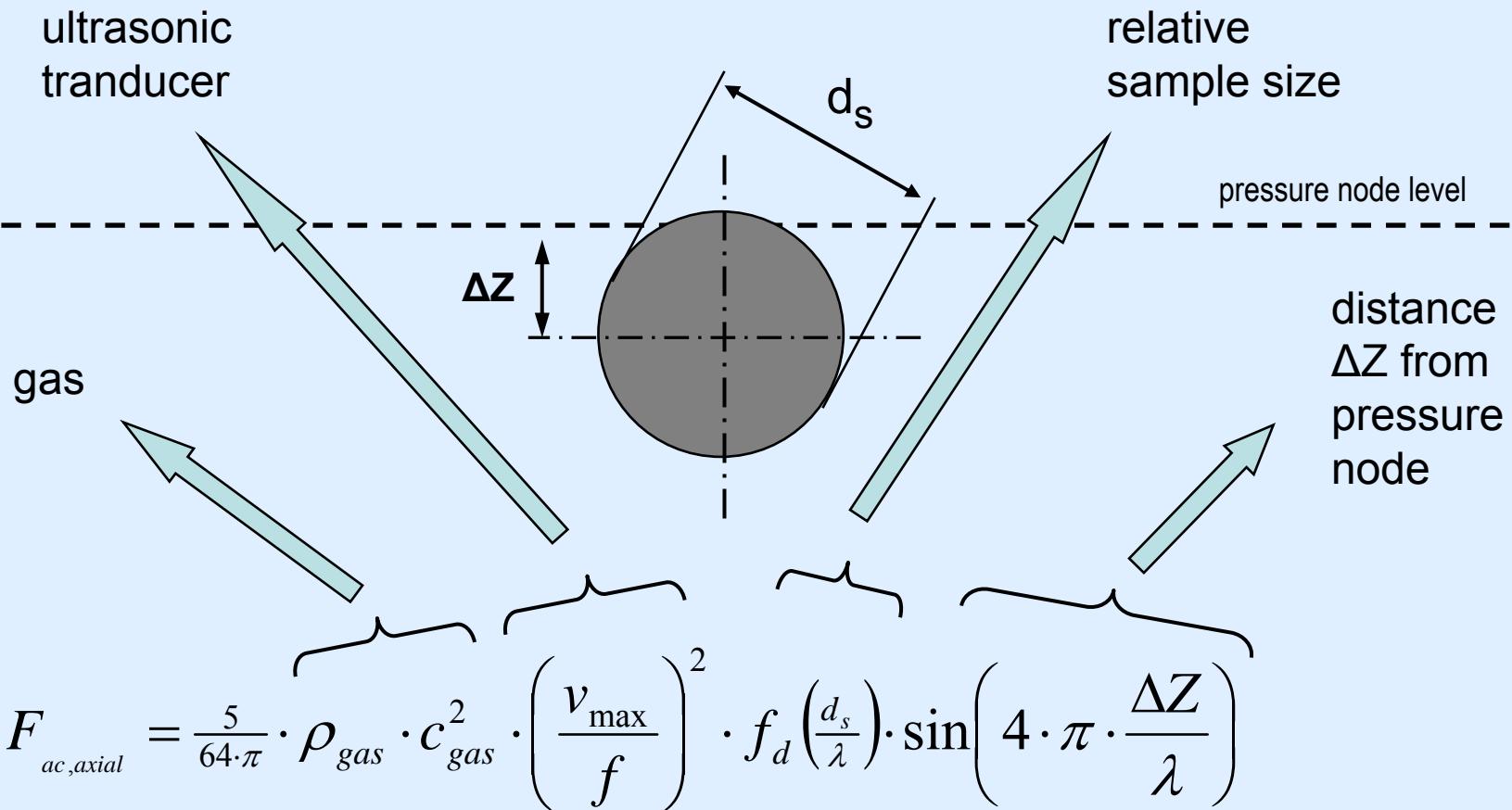


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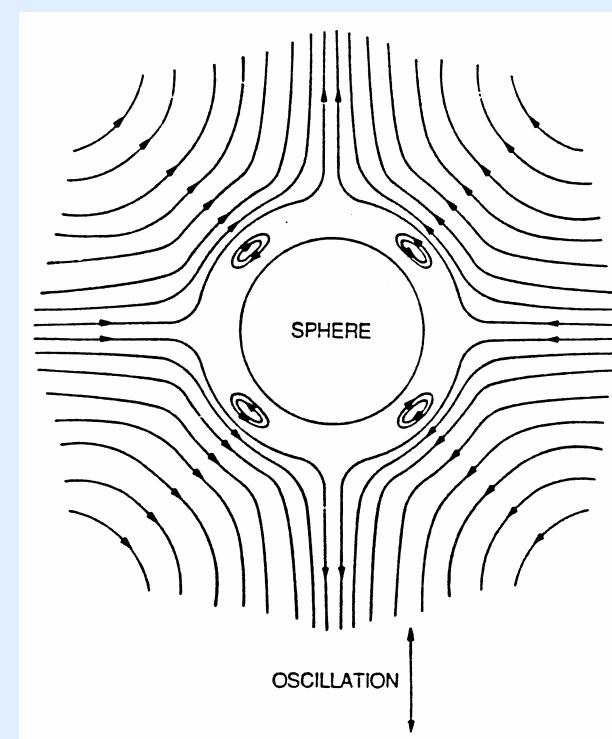
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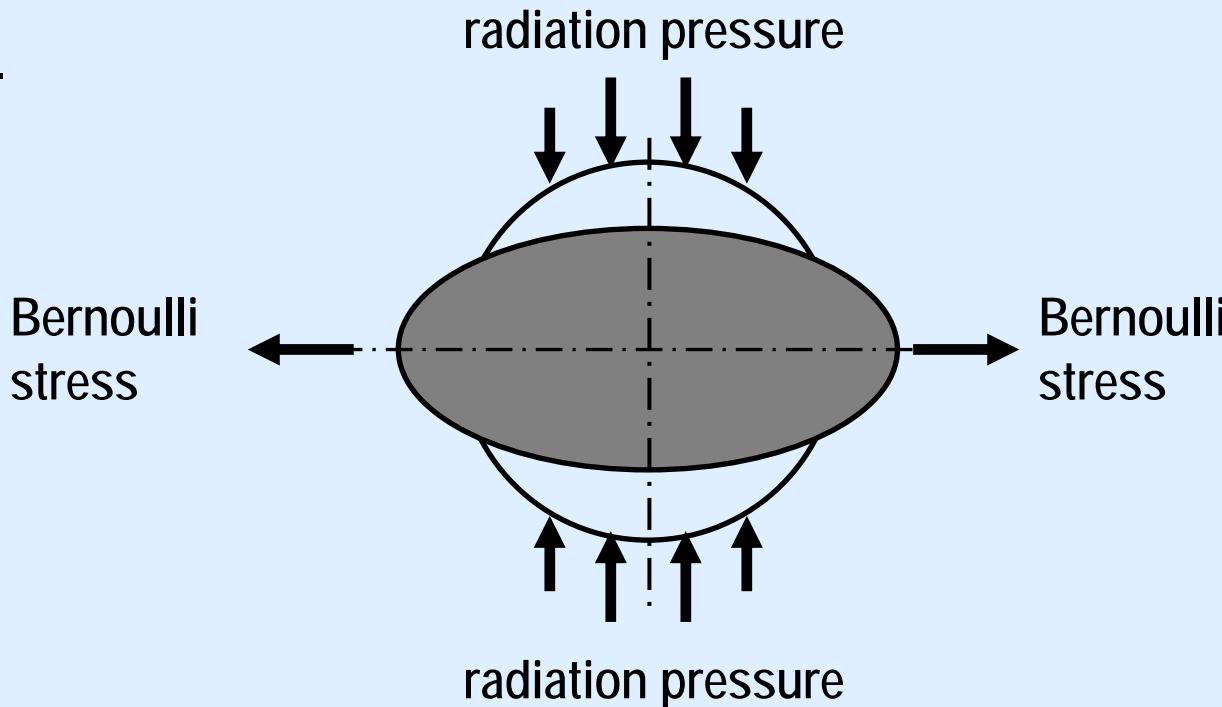
2.2 Typical effects : Acoustic streaming



Side view of the acoustically induced convection near a levitated sphere /1/

/1/ Lee,C.P., Wang, T.G., Outer acoustic streaming, J. Acoust. Soc. Am., 88(5): 2367-2375, 1990

2.2 Typical effects : Deformation of liquid samples



Deformation of a
ac. levitated 35 μ l
water drop /2/

/2/ Holitzner, L., Verbesserung der Funktions-Charakteristik eines elektrostatisch akustischen Hybridlevitators, Diplomarbeit,
FH Wiesbaden, Battelle Institut, Frankfurt/M., 1992

2.2 Typical effects : Heating

Examples :

$d_s = 6 \text{ mm}$ in air @ 20 kHz	water drop (20 °C)	liquid tin (300 °C)	liquid tin (700 °C)
min. sound intensity	2.5 W/cm ²	25.5 W/cm ²	37.2 W/cm ²

2.3 Limiting conditions for : solid samples

a) Sample distance from pressure node

$$F_{ac,axial} \sim \sin\left(4 \cdot \pi \cdot \frac{\Delta Z}{\lambda}\right)$$

$$\sin\left(4 \cdot \pi \cdot \frac{\Delta Z}{\lambda}\right) \leq 1$$

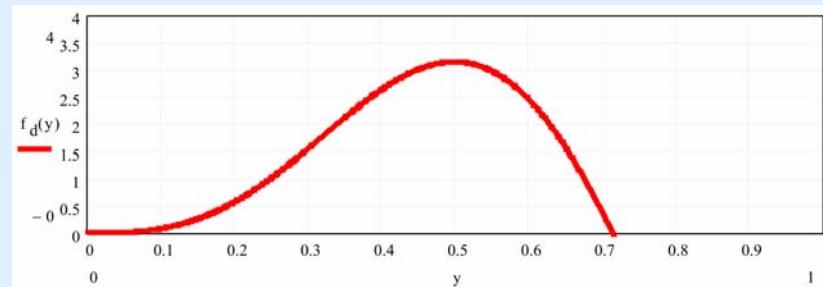
$$\Delta Z \leq \frac{1}{8} \lambda$$

safety factor $\Phi_s = \frac{1}{\sin(4 \cdot \pi \cdot \frac{\Delta Z}{\lambda})} \geq 1$

b) Sample size

$$F_{ac,axial} \sim f_d\left(\frac{d_s}{\lambda}\right)$$

$$f_d\left(\frac{d_s}{\lambda}\right) = \sin\left(2\pi \frac{d_s}{\lambda}\right) - 2\pi \frac{d_s}{\lambda} \cdot \cos\left(2\pi \frac{d_s}{\lambda}\right)$$



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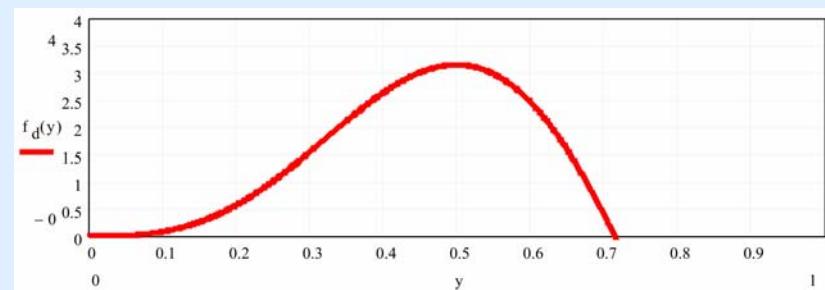
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→ $d_s \leq \frac{1}{2} \lambda = \frac{1}{2} \cdot \frac{c_{gas}}{f}$

2.3 Limiting conditions for : solid samples

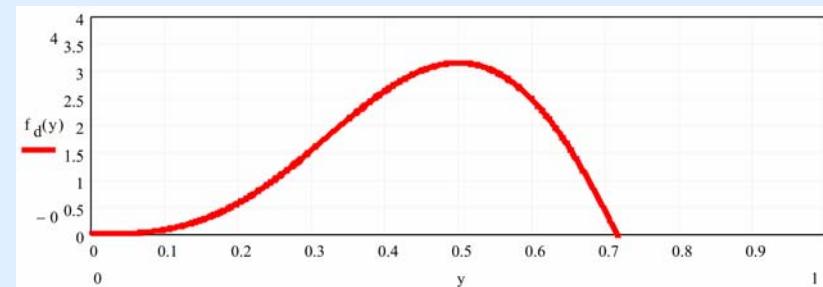
b) Sample size

Examples :

	$d_{s,\max}$ @ 20 °C	$d_{s,\max}$ @ 400 °C
20 kHz in air	8.5 mm	13.0 mm
30 kHz in air	5.7 mm	8.6 mm
60 kHz in air	2.8 mm	4.3 mm
20 kHz in Ar	7.9 mm	
30 kHz in Ar	5.2 mm	

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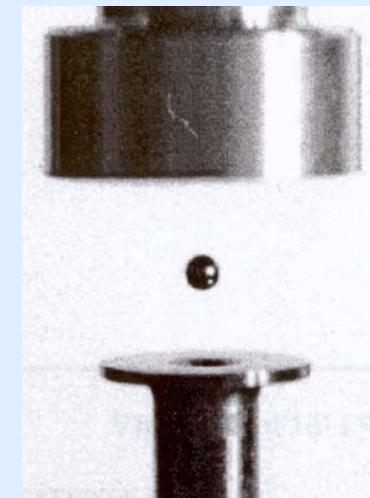
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2.3 Limiting conditions for : solid samples

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2 mm steel sphere
positioned in a
58 kHz levitator /3/

/3/ Schnitzler,A., Aufbau einer akustischen Falle, Joh.
Gutenb.-Uni.Mainz, 1998

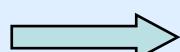
2.3 Limiting conditions for : liquid samples

a) Sample distance from pressure node

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$$\Delta Z \leq \frac{1}{8} \lambda$$



safety factor

$$\Phi_s = \frac{1}{\sin(4 \cdot \pi \cdot \frac{\Delta Z}{\lambda})} \geq 1$$

b) Sample size

$$d_s \leq \frac{1}{2} \lambda$$

$$Bo = \frac{P_{hydrostatic}}{P_{capillary}} = \frac{g}{4} \cdot \frac{\rho_{sample}}{\sigma_{sample}} \cdot d_{sample}^2$$

$$Bo_{acoustic} \leq 1.4$$

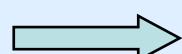
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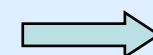
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$$Bo_{acoustic} \leq 1.4$$



$$d_{s,liquid} \leq \sqrt{\frac{5.6}{g} \cdot \frac{\sigma_{sample}}{\rho_{sample}}}$$

2.3 Limiting conditions for : liquid samples

b) Sample size

Examples :

	$d_{s,liquid,max}$	$m_{s,max}$
water (20 °C)	6.4 mm	0.14 g
liquid tin (300°C)	6.6 mm	1.05 g
liquid tin (700 °C)	6.5 mm	0.98 g

$$d_s \leq \frac{1}{2} \lambda$$

$$Bo = \frac{P_{hydrostatic}}{P_{capillary}} = \frac{g}{4} \cdot \frac{\rho_{sample}}{\sigma_{sample}} \cdot d_{sample}^2$$

$$Bo_{acoustic} \leq 1.4$$

$$\rightarrow d_{s,liquid} \leq \sqrt{\frac{5.6}{g} \cdot \frac{\sigma_{sample}}{\rho_{sample}}}$$

2.3 Limiting conditions for : liquid samples

b) Sample size

Examples :

	$d_{s,\text{liquid,max}}$	$m_{s.\text{max}}$
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liquid tin (700 °C)	6.5 mm	0.98 g



Levitated droplets in the 2nd and the 3rd pressure node of a 58 kHz levitator /4/

/4/ Lierke,E.G., Deformation and displacement of liquid drops in optimized acoustic standing wave levitators, Acta acustica, Vol.88 (2002) 206-217

2.4 Optimal conditions : Sound intensity

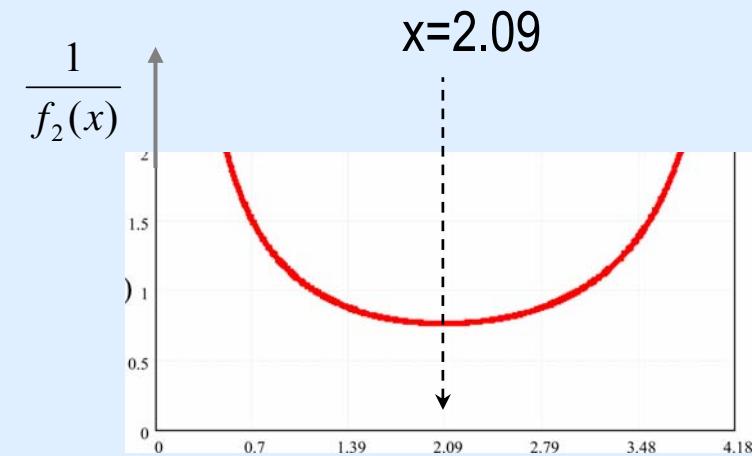
Criterion : minimal necessary sound intensity

sound intensity $J_{sound} = \rho_{gas} \cdot c_{gas} \cdot v_{\max}^2$

min. sound intensity $J_{sound,\min} = \frac{8}{5} \cdot g \cdot c_{gas} \cdot \rho_s \cdot d_s \cdot \frac{1}{f_2(x)}$

with $f_2(x) = \frac{3}{x} \left(\frac{\sin(x)}{x} - \cos(x) \right)$

$$x = 2 \cdot \pi \cdot \frac{d_s}{\lambda}$$



2.4 Optimal conditions : Sound intensity

Criterion : minimal necessary sound intensity

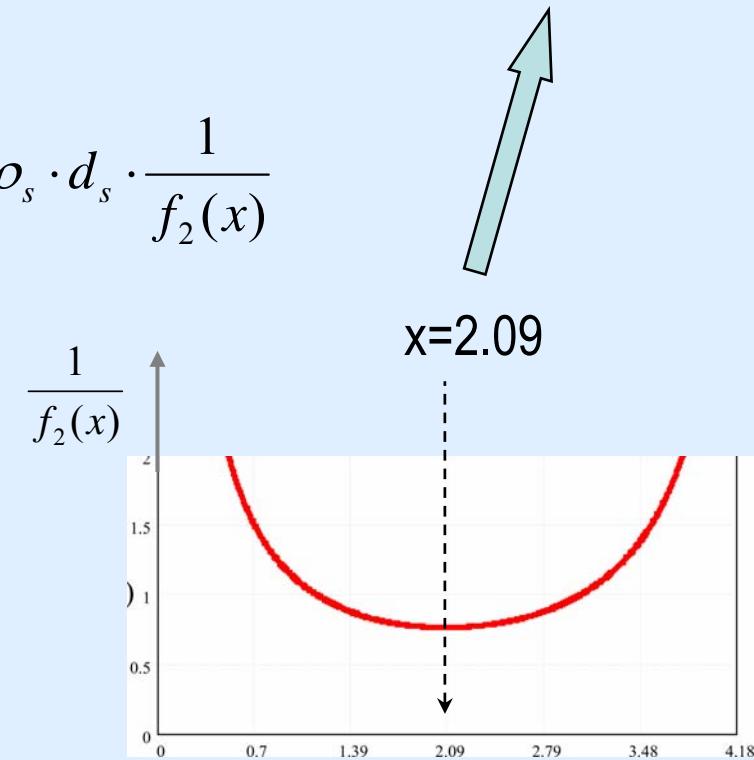
$$\lambda_{s,opt} = 3 \cdot d_s$$

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$$x = 2 \cdot \pi \cdot \frac{d_s}{\lambda}$$



2.4 Optimal conditions : Sample size

Criterion : minimal necessary sound intensity

$$\lambda_{opt} = 3 \cdot d_s = \frac{c_{gas}}{f_{opt}}$$

$$\longrightarrow d_{s,opt} = \frac{1}{3} \cdot \frac{\sqrt{\chi_{gas} \cdot R_{gas} \cdot T_{gas}}}{f}$$

<u>Examples :</u> in air @	20 kHz (20 °C)	30 kHz (20 °C)	40 kHz (20 °C)	20 kHz (300 °C)	20 kHz (700 °C)
d _{s,opt}	5.7 mm	3.8 mm	2.9 mm	8.0 mm	10.4 mm

2.4 Optimal conditions : Sound frequency

Criterion : minimal necessary sound intensity

$$\lambda_{opt} = 3 \cdot d_s = \frac{c_{gas}}{f_{opt}}$$

$$\longrightarrow f_{opt} = \frac{1}{3} \cdot \frac{\sqrt{\chi_{gas} \cdot R_{gas} \cdot T_{gas}}}{d_{s,max}}$$

Examples :

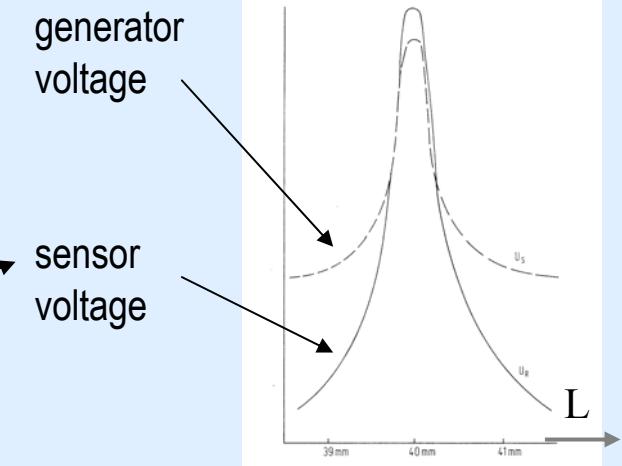
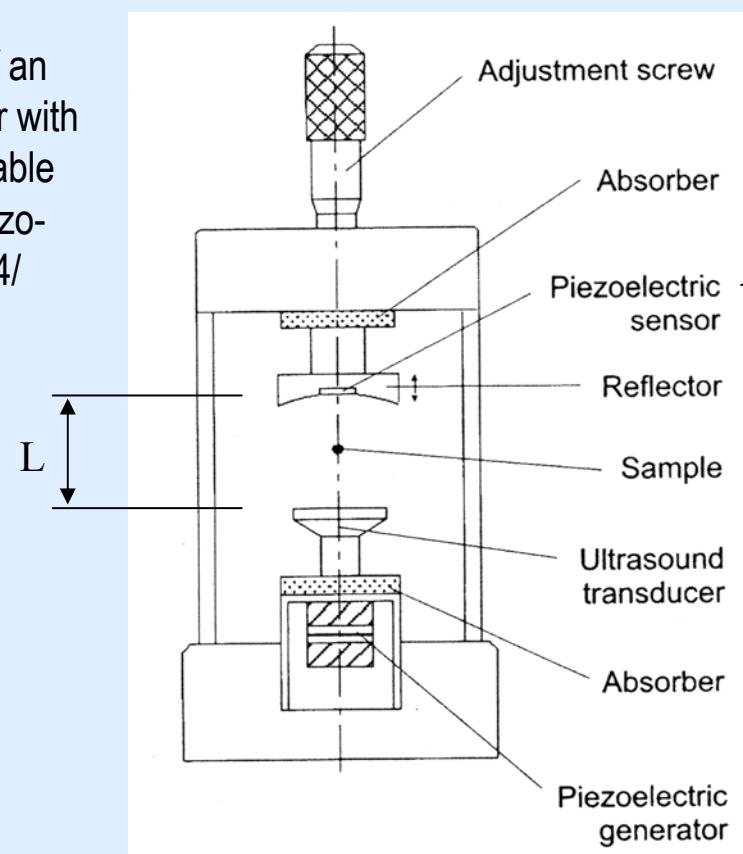
in air @

	water (20 °C)	water (80 °C)	liquid tin (300 °C)	liquid tin (700 °C)
f_{opt}	17.8 kHz	19.6 kHz	24.1 kHz	31.6 kHz

3. Application and instrumentation

3.1 State of the art : Environment

- Typical layout of an acoustic levitator with manually adjustable reflector and piezoelectric sensor /4/

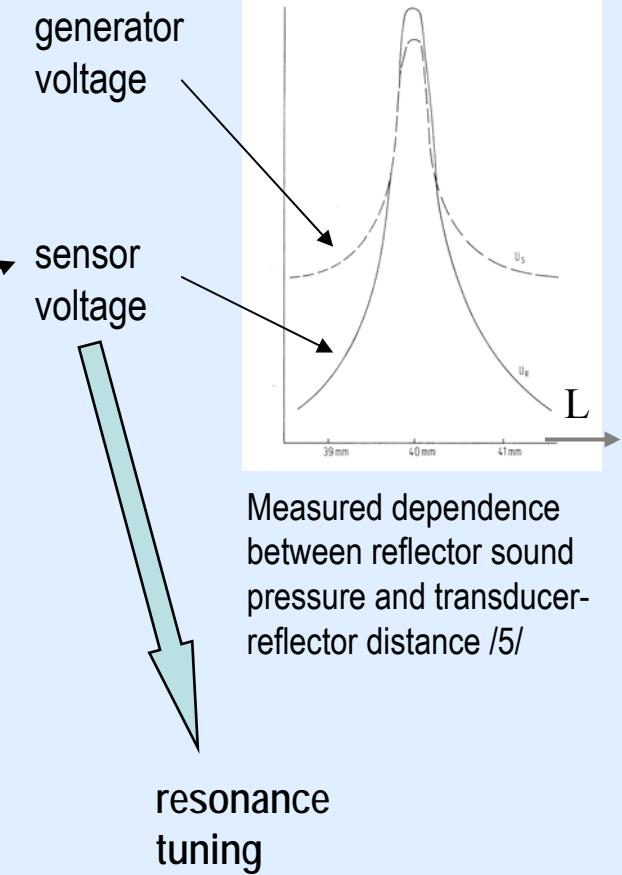
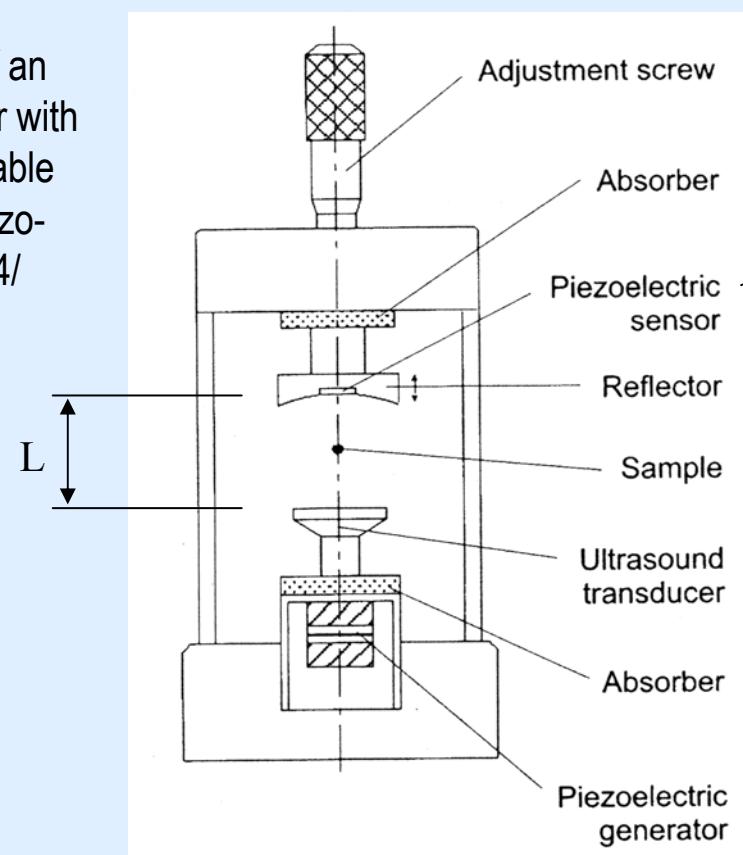


Measured dependence between reflector sound pressure and transducer-reflector distance /5/

/4/ Lierke,E.G., Acta acustica, Vol.88 (2002) 206-217

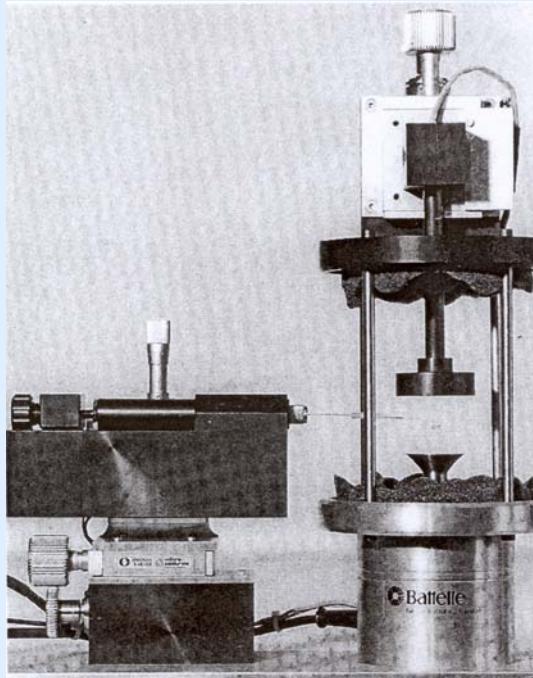
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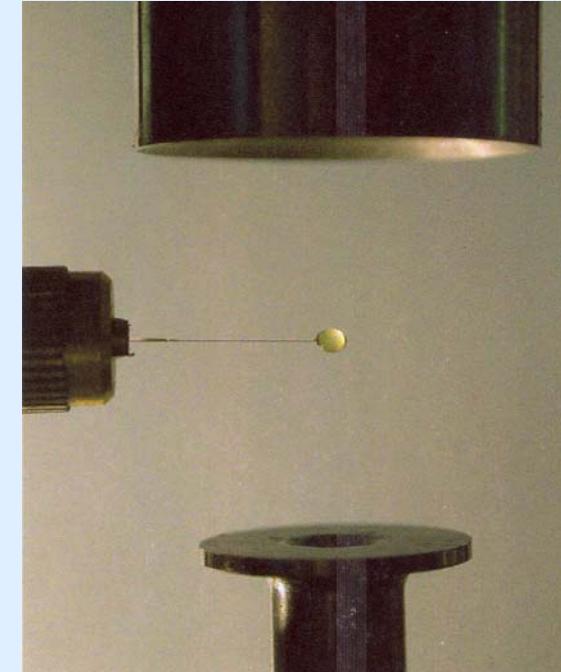
/4/ Lierke,E.G., Acta acustica, Vol.88 (2002) 206-217

3.1 State of the art : Environment



20kHz levitator with droplet injector and automatic resonance tuning /5/

/5/ Lierke, E.G., Akustische Positionierung – Ein umfassender Überblick über Grundlagen und Anwendungen, Acustica – acta acustica, Vol. 82 (1996) 220-237

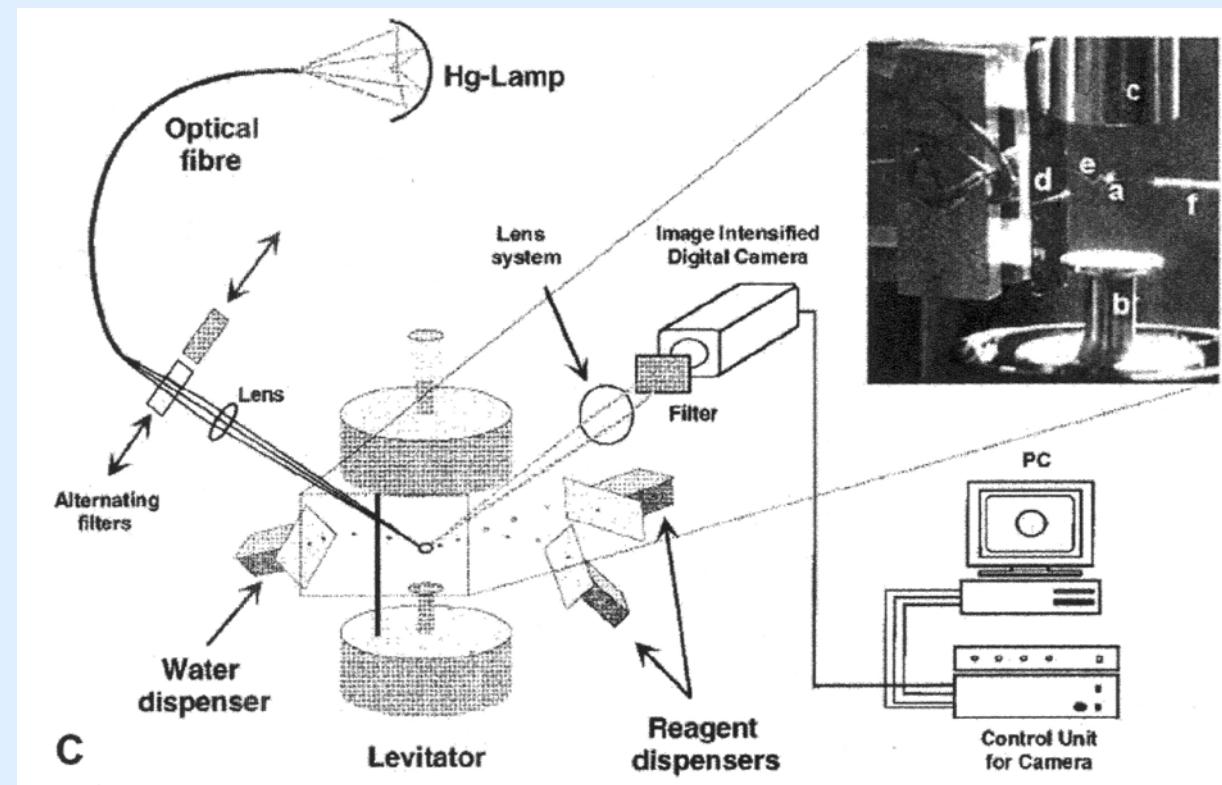


Droplet implementation into a 58kHz levitator by drain tube /6/

/6/ Sprynchak, V., Ramanspektroskopische Unters. a. homog. u. inhomog. sphärischen u. sphäroiden Partikeln, Dissertation, Fak. f. Maschinenbau d. Ruhr-Universität Bochum, 2003

3.1 State of the art : Environment

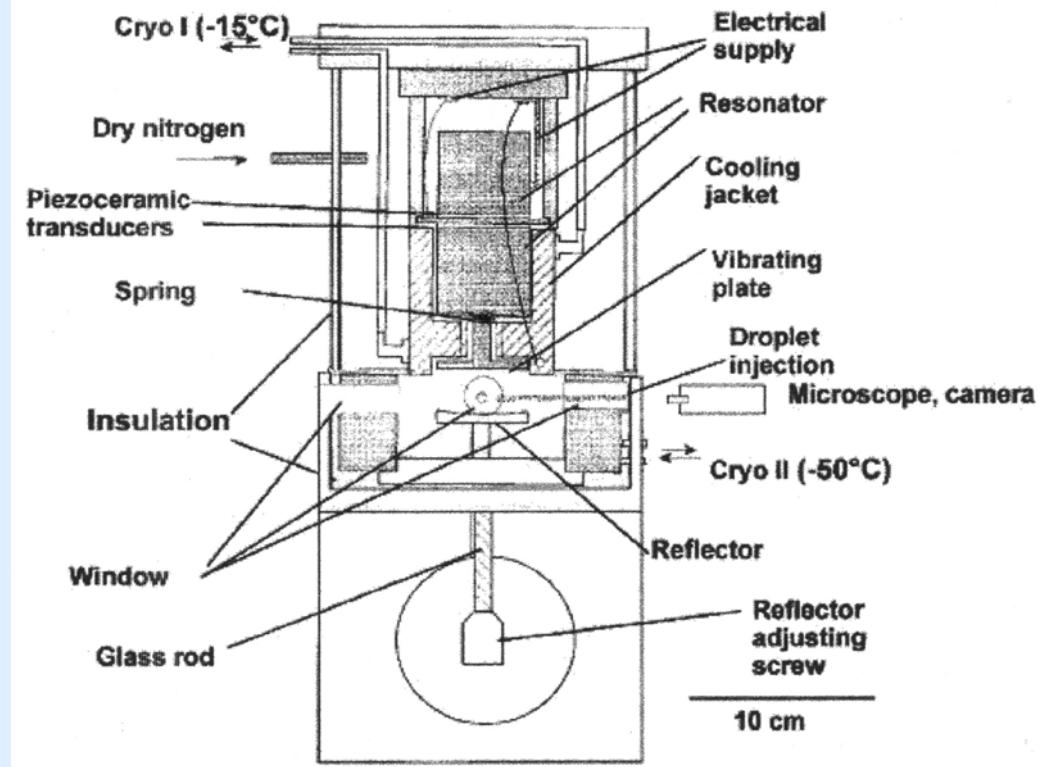
Acoustic levitator
for bioanalytical
applications at
0...70 °C,
100 kHz /7/



/7/ Santesson, M., Andersson, E., Degerman, T., Johansson, J. Nilsson, S., Anal. Chem. 72 (2000) 3412

3.1 State of the art : Environment

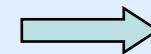
Upside down acoustic levitator for „cryo applications“ -55...0 °C /8/



/8/ Jacob, P., Stockhaus, R., Hergenröder, D., Klockow, Fresenius' J. Anal. Chem. 371 (2001) 726

3.1 State of the art : Temperature range

main temperature range :	(approx.)	+15 °C ... +70 °C	(lamp)
extended temp. range :	(today, approx.)	-100 °C ... +80 °C	(cooled / heated gas)
highest temperatures :	(today, approx.)	+400 °C	(mirror furnace)

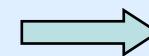


Gas mixing systems /9/

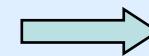
/9/ Lierke, E.G., Bessel-mode levitation in cyl. tubes at variable temperatures and pressures, Ultrasonics world congress 1995 proceedings, Berlin, Vol.2 (1995), 811-814

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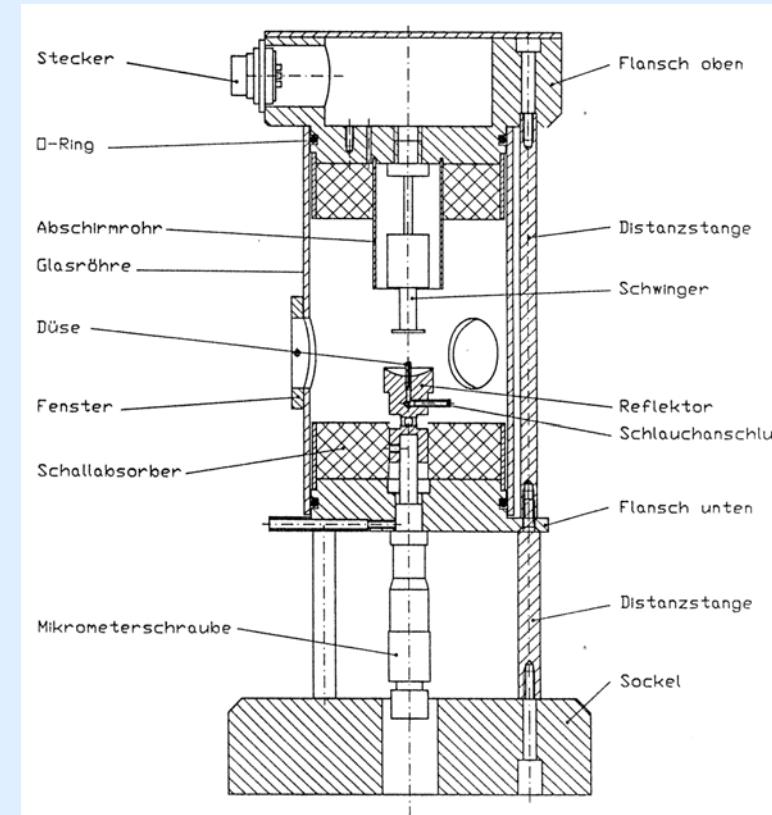


Hybrid levitators

/9/ Lierke, E.G., Bessel-mode levitation in cyl. tubes at variable temperatures and pressures, Ultrasonics world congress 1995 proceedings, Berlin, Vol.2 (1995), 811-814

3.2 Capabilities : Hybrid levitators

Aerodynamic-acoustic
hybrid levitator /10/



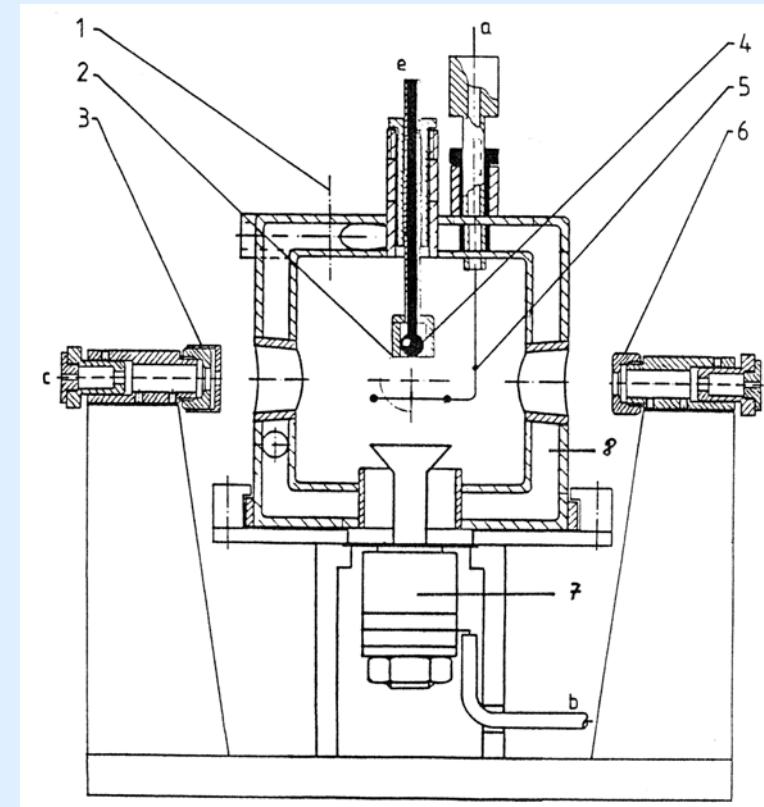
/10/ Lierke, E.G., private communications

3.2 Capabilities : Hybrid levitators

Electrostatic-acoustic hybrid levitator for controlled drop evaporation and condensation /2/



electrostatically levitated
35 μ l water drop /2/



- 1 - temperature and humidity sensor
- 2 - sound reflector
- 3 - optical position sensor (6)
- 4 - field electrode
- 5 - charging electr.
- 7 - ultrasonic transd.
- 8 - process. chamber

/2/ Holitzner, L., Diplomarbeit, FH Wiesbaden, Battelle Institut, Frankfurt/M., 1992

3.2 Capabilities : Further applications

- magnet field
- pressure

4. Engineering and design parameters

4.1 Soundfield : Vertical take off angle

The angle depends on :

- distance between transducer and reflector (number of pressure nodes, λ)
- sample position (position number of the pressure node)
- reflector diameter
- transducer diameter

4.1 Soundfield : Resonance amplification

$$\left| \frac{v_{\max}}{v_{t,\max}} \right| = \cosh \frac{n \cdot \frac{z}{l} \cdot \pi}{2 \cdot Q} \cdot \left(\sinh \frac{n \cdot \pi}{2 \cdot Q} \right)^{-1}$$

Q – quality factor (= typ. 80...100)

n – number of pressure nodes

z/l – rel. position of the sample in the standing wave

Example :

Q = 81 (measured)

n = 5

sample in the 3rd pressure node : z/l = 0.5

$$\longrightarrow \left| \frac{v_{\max}}{v_{t,\max}} \right| \approx 10.3$$

typical for water drops @ 20 kHz:

$$v_{\max} = 10 \text{ m/s} \rightarrow v_{t,\max} \approx 1 \text{ m/s}$$

$$A_t = v_{t,\max} / 2\pi f \approx 8 \mu\text{m}$$

Conclusion

Thank you